

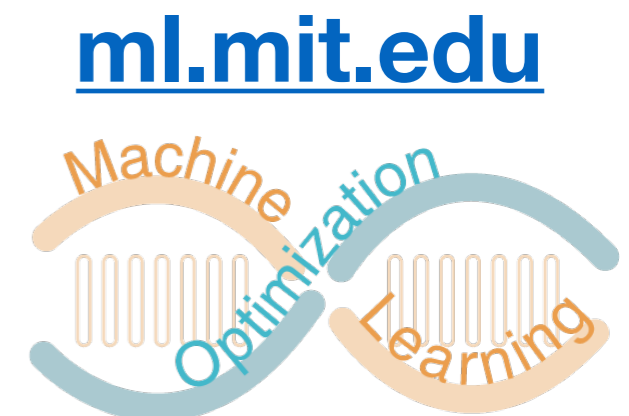
Negative Dependence, Stable Polynomials etc in ML

Part 2

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Outline

1

Intro &
Theory

Introduction

Prominent example: Determinantal Point Processes

Stronger notions of negative dependence

Implications: Sampling

2

Theory &
Applications

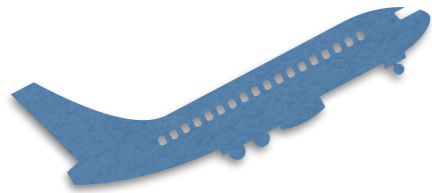
Approximating partition functions

Learning a DPP (and some variants)

Applications

Recommender systems, Nyström method, optimal design, regression, neural net pruning, negative mining, anomaly detection, etc.

Perspectives and wrap-up



Theory



Partition functions

Learning DPPs

Computing Partition functions

Aim: Estimate Z_μ , i.e., normalization const / partition function

$$\Pr(S) = \frac{1}{Z_\mu} \mu(S)$$



Typically intractable and often even hard to approximate

(exponential number of terms to sum over, or evaluation of high-dimensional integrals / volumes)

but...

Computing Partition functions



Nature makes an exception for DPPs!

$$Z_L = \sum_{S \subseteq [n]} \det(L_S) = \det(I + L)$$

What about?

$$Z_\mu = \sum_{S \subseteq [n]} \mu(S) \quad (\text{SR})$$

$$Z_{\mu,p} = \sum_{S \subseteq [n]} \mu(S)^p \quad (\text{ESR})$$

Computing Partition functions

$$Z_{\mu} = \sum_{S \subseteq [n]} \mu(S), \quad Z_{\mu,p} = \sum_{S \subseteq [n]} \mu(S)^p$$

Using properties of stable polynomials, these can be approximated within factor e^n (e^k for k-homogeneous, e.g., k-DPP): [Straszak, Vishnoi, 2016; Nikolov, Singh, 2016; Anari, Gharan, Saberi, Singh, 2016; Anari, Gharan 2017]

Key: Build on Leonid Gurvits' fundamental work (2006) on approximating permanents of nonnegative matrices using convex relaxation afforded by stable polynomials

$$\inf_{z > 0} \frac{p(z_1, \dots, z_n)}{z_1 z_2 \cdots z_n}$$

$z = \exp(y)$: yields convex optim.

(a geometric program - GP)

Example: matrix permanents

$$\text{per}(A) = \sum_{\sigma \in \mathfrak{S}_n} \prod_{i=1}^n a_{i, \sigma(i)}$$

Eg: counts number of perfect matchings in a bipartite graph



A is
doubly
stochastic

Permanents via stable polynomials (Gurvits 2006)

$$\text{per}(A) = \frac{\partial^n p(0)}{\partial z_1 \cdots \partial z_n}$$

$$p(z_1, \dots, z_n) = \prod_{i=1}^n \left(\sum_{j=1}^n a_{ij} z_j \right)$$

$$\frac{\partial^n p}{\partial z_1 \cdots \partial z_n} \geq \frac{n!}{n^n} \inf_{z > 0} \frac{p(z_1, \dots, z_n)}{z_1 z_2 \cdots z_n}$$

Learning

Learning a DPP from data

Aim: Learn a DPP kernel matrix from data

More generally: Learn an SR measure from data (how?)

Application: Learn from observed subsets to be able to “recommend” or perform “subset selection”

Originally studied in:

Kulesza, Taskar ICML 2011, UAI 2011

Affandi, Fox, Adams, Taskar, ICML 2014

Gillenwater, Kulesza, Fox, Taskar, NIPS 2014



MLE for learning a DPP

Given observations Y_1, \dots, Y_N (subsets of $[n]$)

$$\max_{L \succ 0} \phi(L) := \sum_{i=1}^N \log \Pr(Y_i) = \sum_{i=1}^N \log \frac{\det(L_{Y_i})}{\det(I + L)}$$

Amazingly simple algorithm *[Mariet, Sra, 2015]*

$$L \leftarrow L + L \nabla \phi(L) L$$



Related recent work

- Asymptotic properties of MLE for DPPs: *[Brunel, Moitra, Rigollet, Urschel, 2017]*
- Learning a DPP via method of moments to achieve near optimal sample complexity: *[Urschel, Brunel, Moitra, Rigollet, ICML 2017]*

Speeding up DPP learning

Challenge: Basic $L+L\phi'(L)L$ iteration costs n^3 , avoid?

k-DPP: Restrict DPP to subsets of size exactly 'k'

[Kulesza, Taskar, 2011]

LR-DPP: Write $L=VV^T$ for low-rank V (can sample size $\leq k$)

[Gartrell, Paquet, Koenigstein, 2017]

Kron-DPP: Write $L = L_1 \otimes L_2$ (can sample any size)

[Mariet, Sra, 2017]

among others...

Open problems: learning



Problem 1: Learning parametrized classes of other SR measures

Problem 2: Efficiently learn a “Power-DPP”, i.e., $\mu(S) = \det(L_S)^p$

Problem 3: Learn the diversity tuning parameter ‘p’ in Power-DPPs and more generally in Exponentiated SR measures

Problem 4: Explore other learning models; e.g. Deep-DPP to learn nonlinear features for a DPP [Gartrell, Dohmatob, 2018], or “negative mining” for reducing overfitting [Mariet, Gartrell, Sra, 2018]

Applications



Recommender systems

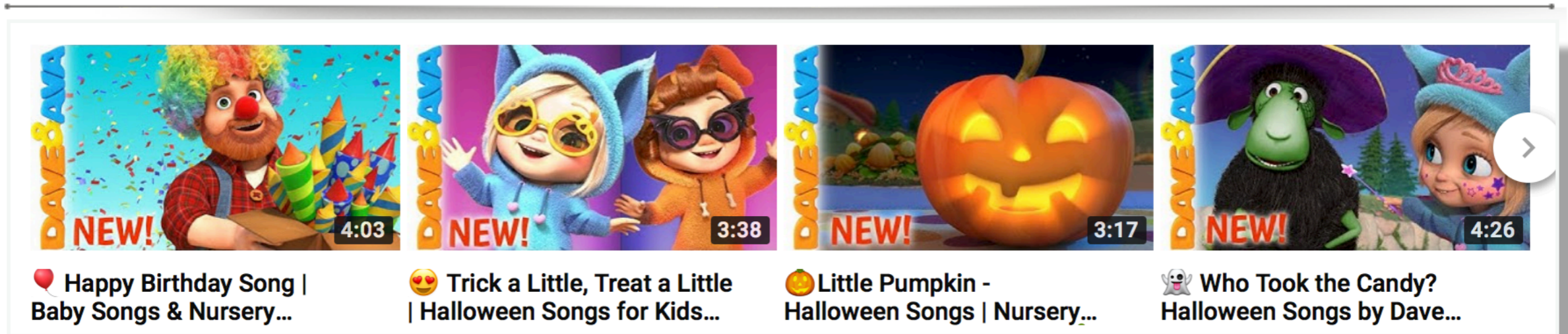
Model compression

Nystrom approximation

Outlier detection

Optimal design

Recommender systems



Practical Diversified Recommendations on YouTube with Determinantal Point Processes

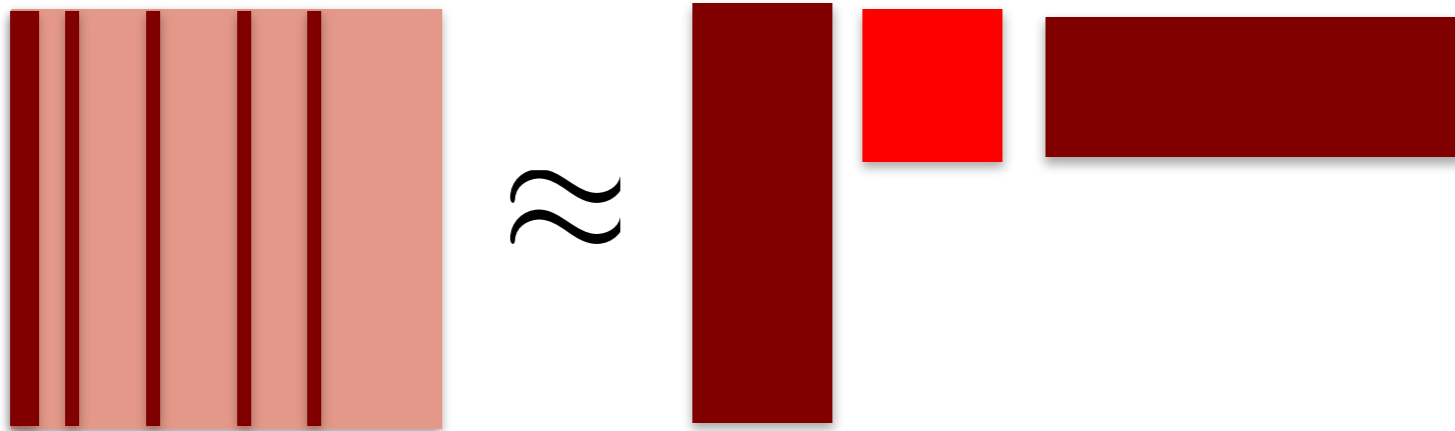
Mark Wilhelm, Ajith Ramanathan, Alexander Bonomo, Sagar Jain, Ed H. Chi, Jennifer Gillenwater

- Challenges:**
- Handling mismatch between model's notion of diversity versus user's perception of diversity (true for other applications too)
 - Scalability to large-scale data
 - Integrating within existing recommender ecosystems (e.g. existing pointwise recommenders vs DPP's setwise!)

See also monograph and tutorial by A. Kulesza for more!

Nyström approximation

- Fundamental tool for scaling up kernel methods



- Which columns (data points)?

(Williams & Seeger 01, Zhang et al 08, Belabbas & Wolfe 09, Gittens & Mahoney 13, Alaoui & Mahoney 15, Deshpande et al 06, Smola & Schölkopf 00, Drineas & Mahoney 05, Drineas et al 06, ...)

- Sample subset S from k -DPP

$$\hat{K} = K_{:,S} K_{S,S}^\dagger K_{S,:}$$

Nyström approximation

- Sketching matrices/kernel methods

$$\widehat{K} = K_{:,S} K_{S,S}^\dagger K_{S,:}$$

Theorems. (Li, Jegelka, Sra 2016)

$$\frac{\mathbb{E}[\|K - \widehat{K}\|_F]}{\|K - K_k\|_F} \leq \frac{c+1}{c+1-k} \sqrt{N-k}$$

Approx quality
 $c \geq k$ landmarks

$$\mathbb{E} \sqrt{\frac{\mathcal{R}(\hat{z})}{\mathcal{R}(\hat{z}_S)}} \geq 1 - \frac{c+1}{N\gamma} \frac{e_{c+1}(K)}{e_c(K)}$$

Expected risk
kernel ridge regression

ratio of elementary symm. polynomials

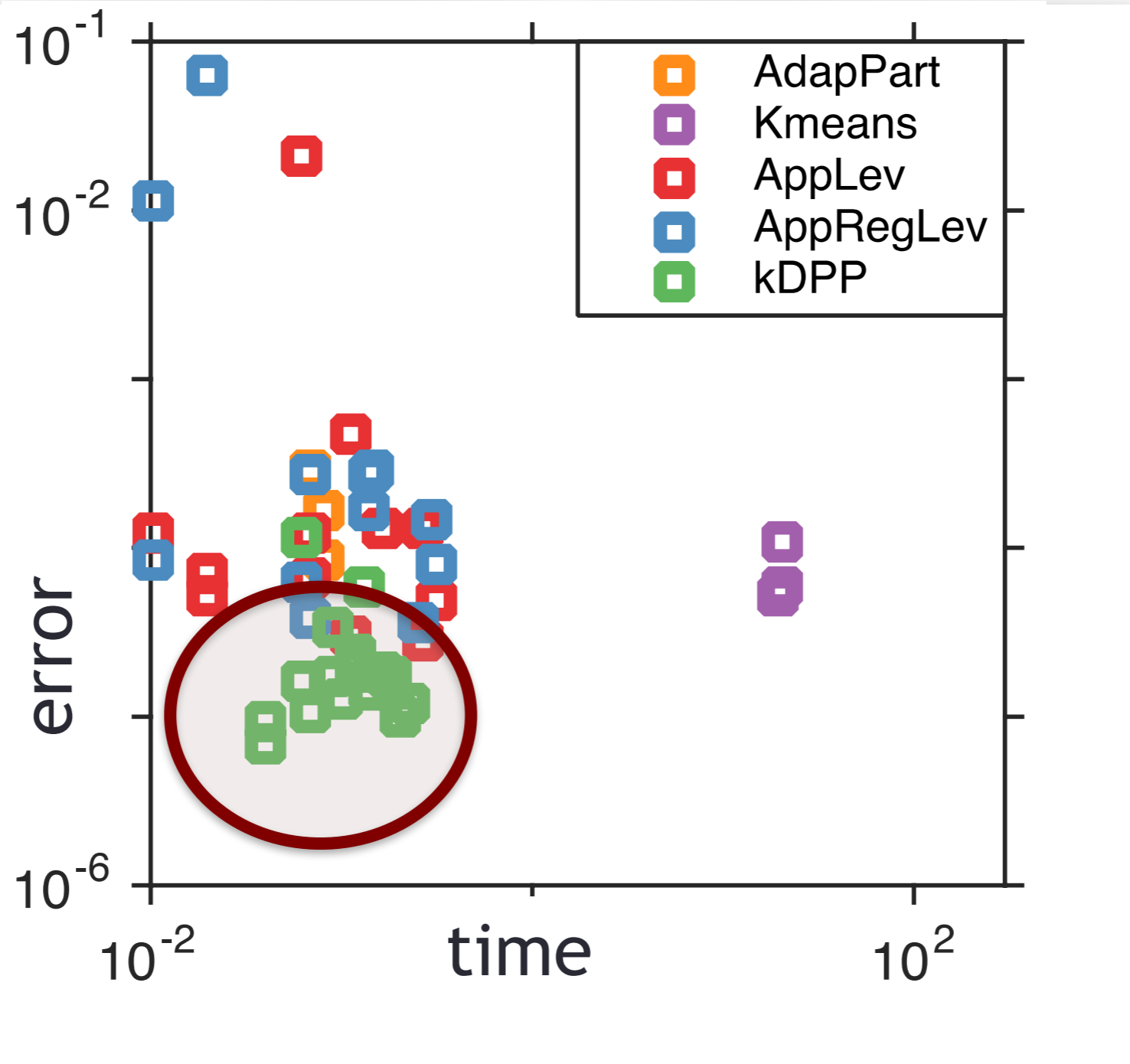
Nyström approximation

- Sketch

Theorems.

$$\frac{\mathbb{E}[\|K - \hat{K}\|]}{\|K - K_k\|}$$

$$\mathbb{E} \sqrt{\frac{\mathcal{R}(\hat{z})}{\mathcal{R}(\hat{z}_S)}}$$

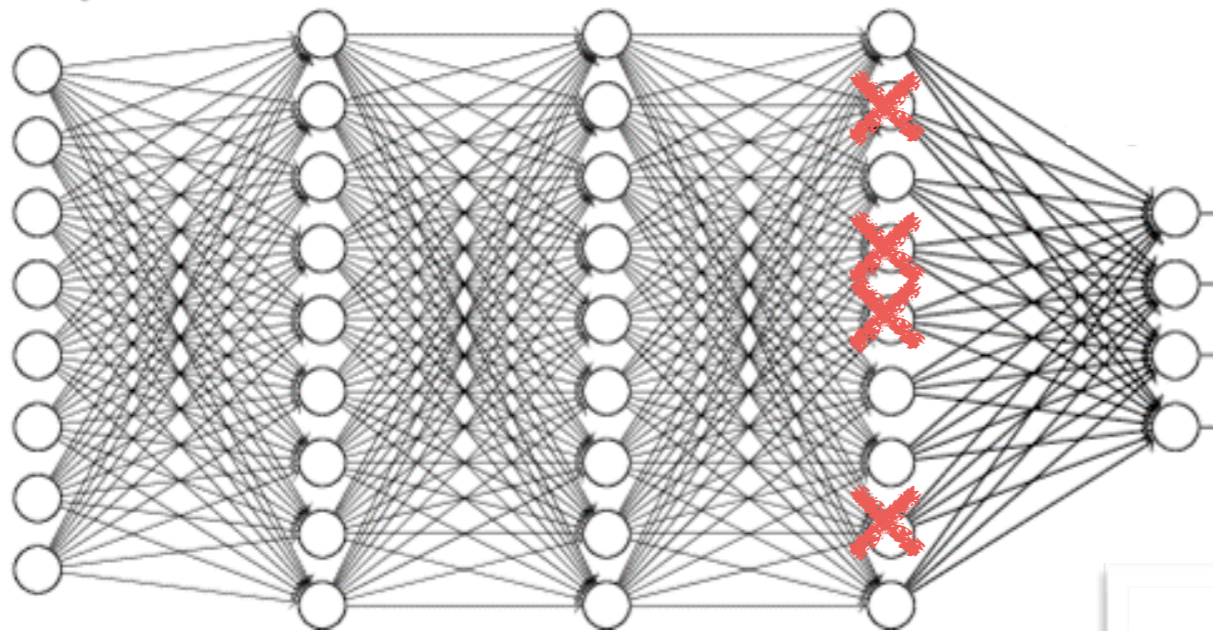


x quality
landmarks

ed risk
ridge regression

(Li, Jegelka, Sra 2016) *ratio of elementary symm. polynomials*

Neural network pruning

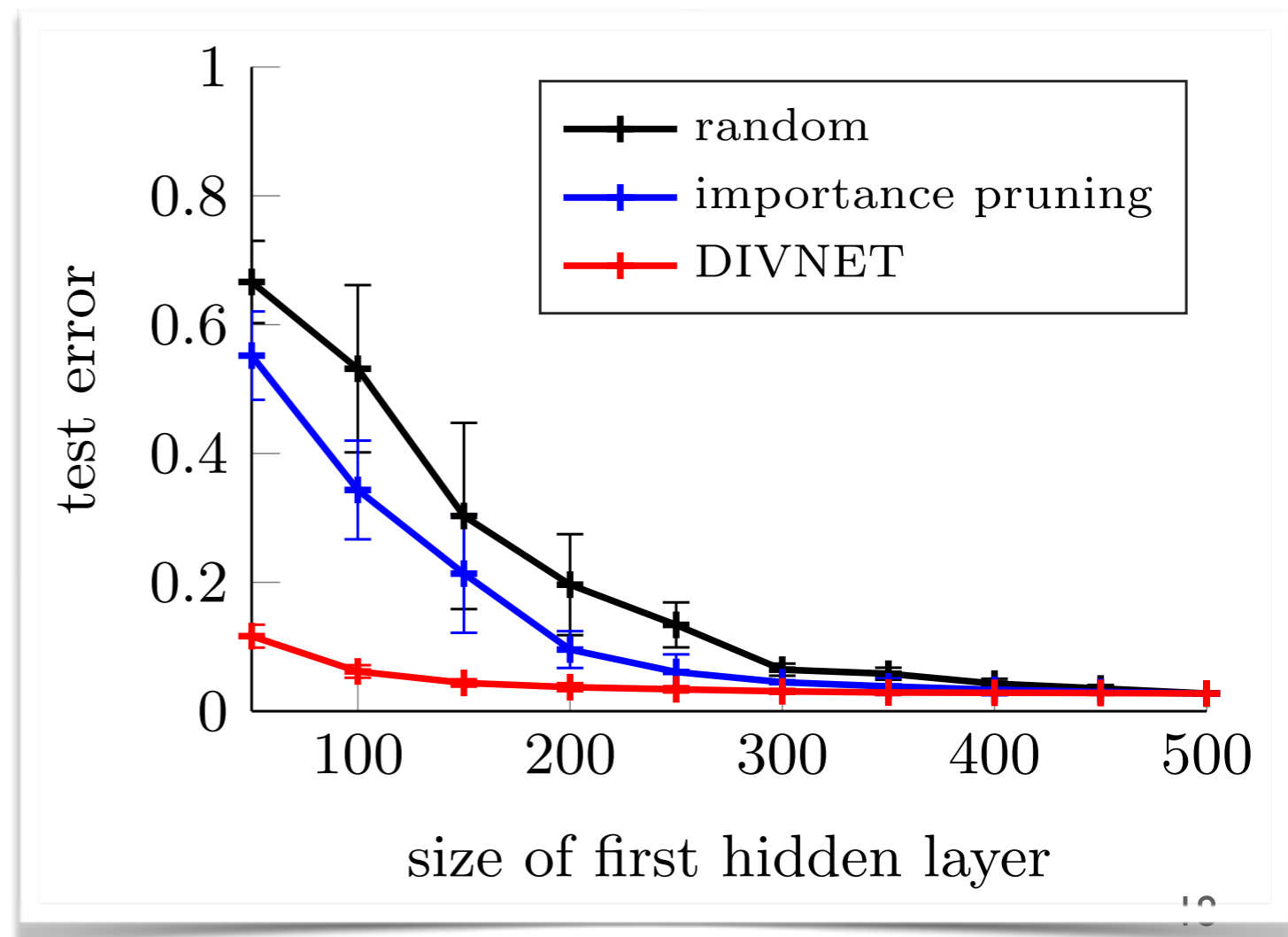


Challenge: Which measure to use for sampling?

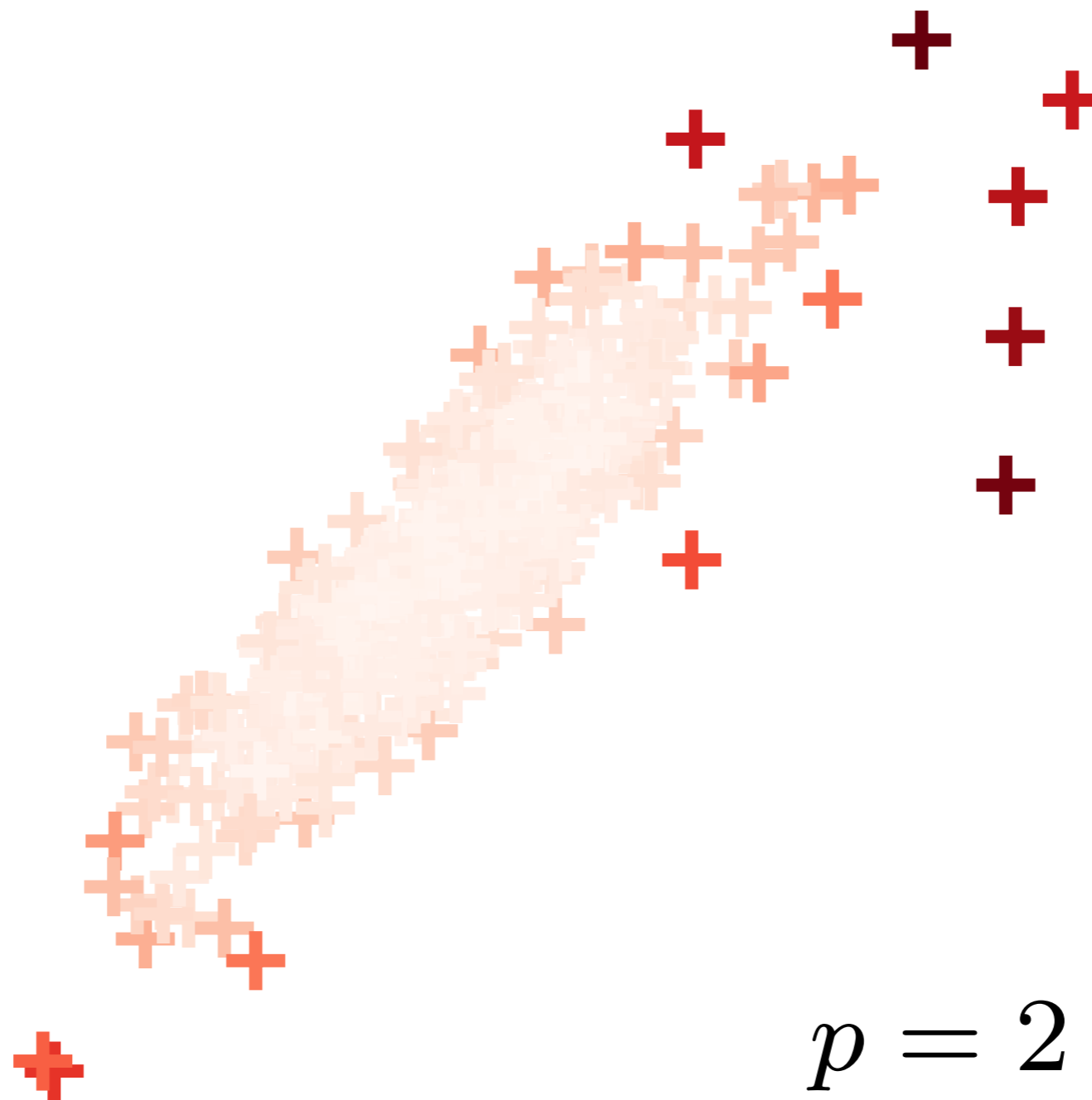
“Diversity networks”

1. Sample diverse neurons
2. Delete redundant ones
3. Rebalance layer output

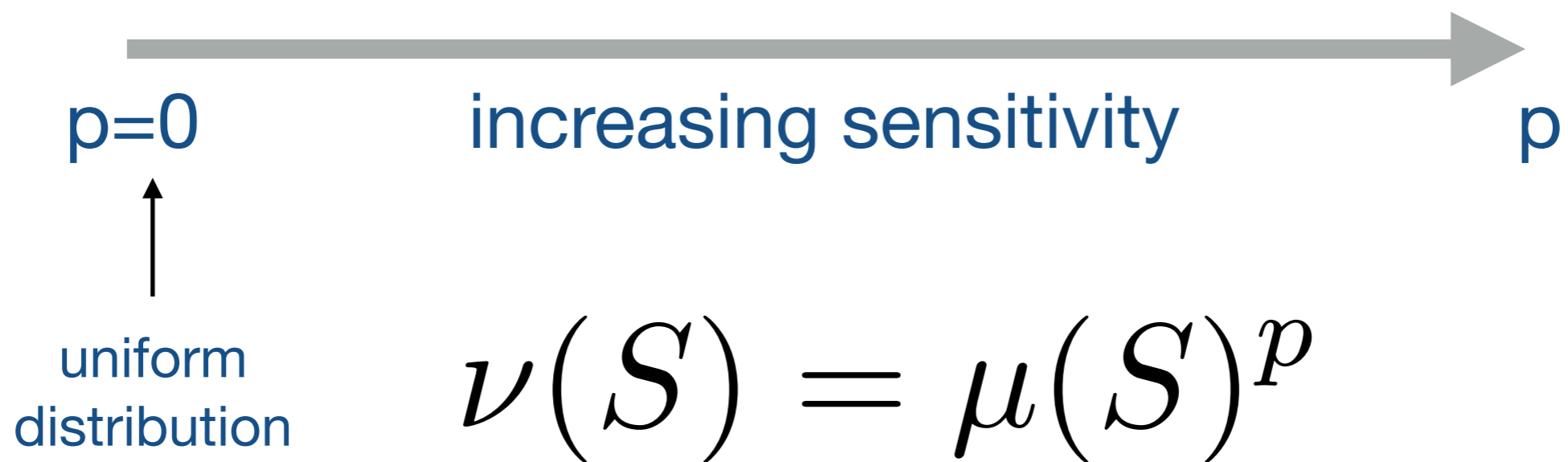
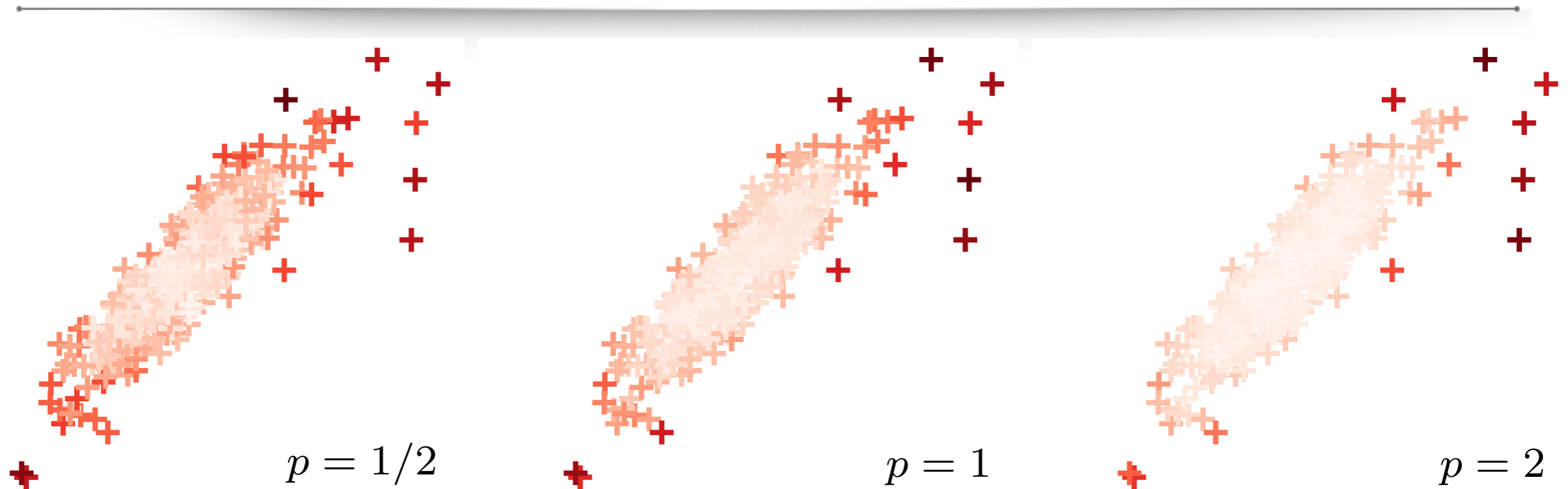
(Mariet, Sra 2016)



Outlier detection

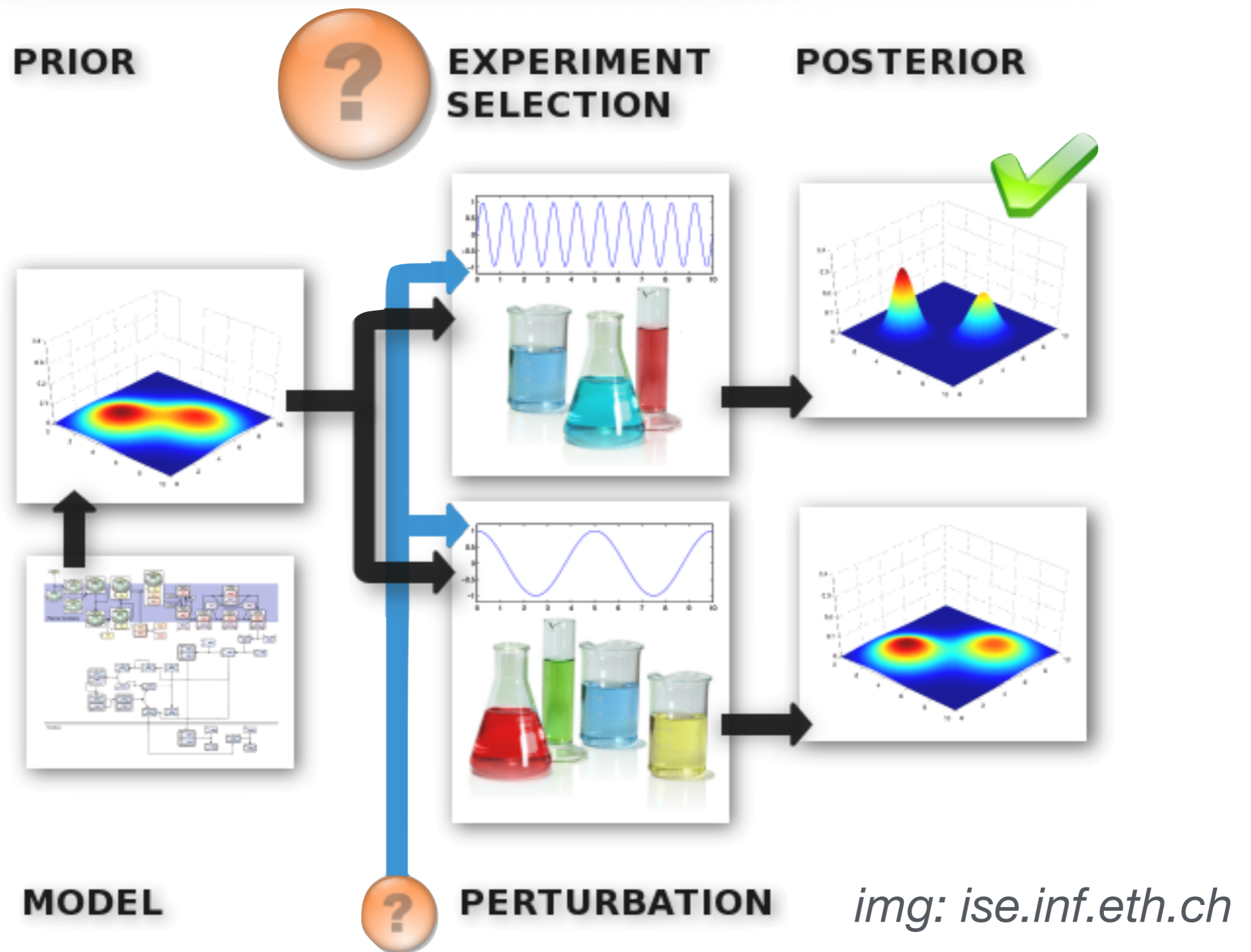
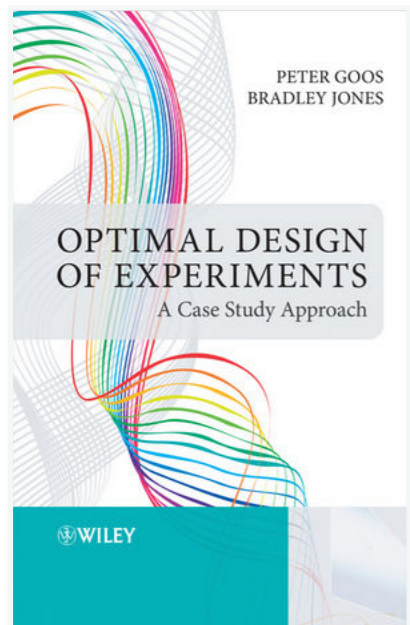


Outlier detection



[Mariet, Sra, Jegelka, 2018]

Optimal design & active learning



Optimal design & active learning

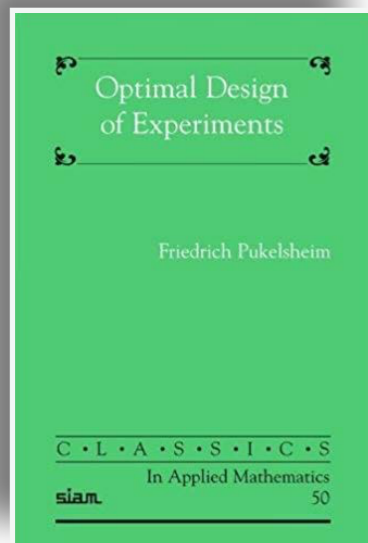
Setup: Say ‘m’ possible experiments with measurements x_1, \dots, x_m , (with x_i in \mathbb{R}^n), and scalar outcomes y_1, \dots, y_m

$$y_i = \theta^T x_i + \epsilon$$

Aim: Pick a subset S of $[m]$ to “minimize” uncertainty

$$\min_{S \subseteq [m], |S|=k} \Phi \left(\left(\sum_{i \in S} x_i x_i^T \right)^{-1} \right)$$

What is this?



Ref. Pukelsheim, *Optimal design of experiments*.

Optimal design & active learning

$$\min_{S \subseteq [m], |S|=k} \Phi \left(\left(\sum_{i \in S} x_i x_i^T \right)^{-1} \right)$$

Φ =trace gives A-optimal, Φ =det gives D-optimal design

(Wang, Yu, Singh, 2016)

(Bayesian A-opt: Golovin, Krause, Ray, 2013)

(Chamon, Ribeiro, 2017)

(Chen, Hassani, Karbasi, 2018)

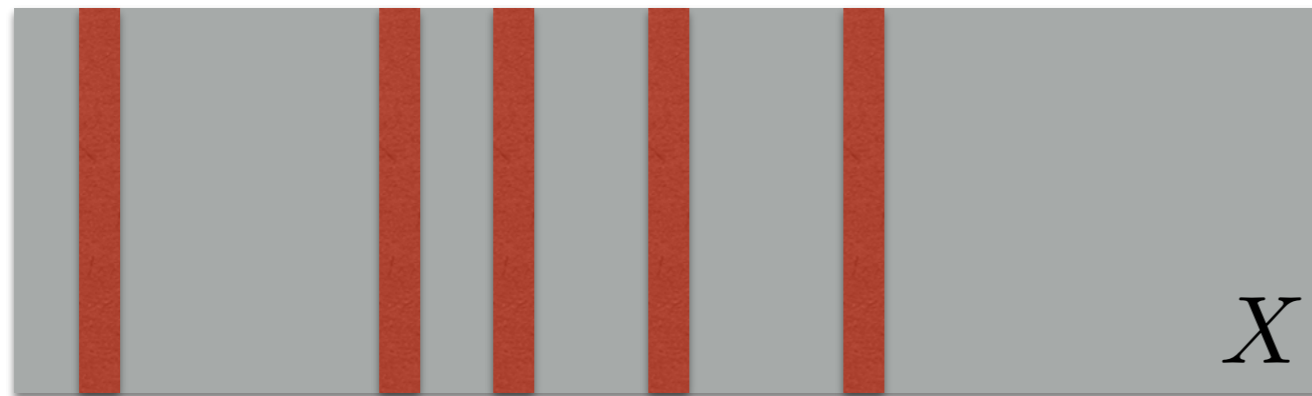
(Singh, Xie, 2018)

...and many more

(Mariet, Sra, 2017): Φ =Elementary Symmetric Polynomial
(recovers A- and D-optimal case extreme cases)

Thm. Greedy algo and convex relaxation both work.
Success of greedy uses “Dual” volume sampling!

“Dual” volume sampling



$$P(S) \propto \det(X_S X_S^T)$$

NOT a DPP
...but SR

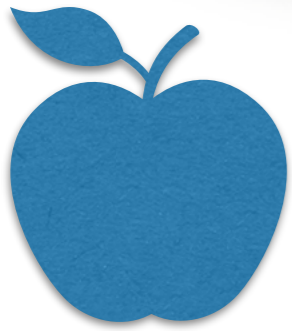
n rows, $m \gg n$ columns. Sample $k > n$ columns.

(Avron & Boutsidis 2013): approximation bounds on Frobenius norms for A-/E-optimal experimental design from sampling.

(Mariet, Sra, 2017) generalize to E-Symm. Polynomials

Note: *(Derezinski, Warmuth, 2017)* and *(Li, Jegelka, Sra, 2017)* provide efficient algorithms to sample from $P(S)$

Optimal design & active learning



An aside for convex optimization folks

Dual of convex relaxation to D-optimal design is the famous MVCE problem (Todd, *Minimum Volume Ellipsoids* SIAM 2016)

$$\max \log \det(M), \quad M \succ 0, \quad \|Ma_i - z\| \leq 1, \quad 1 \leq i \leq N$$

Uncovers a connection between geometry, optimization, and optimal-design (and hence stable polynomials!)



Hence, similar geometric problems via duals of convex relaxations of the Φ -optimal design problems (prev. slide)

Other ML applications

- ★ See past tutorials on submodular models in ML (various authors)
- ★ Reinforcement learning (diversity based exploration)
<https://arxiv.org/abs/1802.04564>
- ★ Fairness and diversity
<https://arxiv.org/abs/1610.07183>
- ★ Video Summarization
<https://arxiv.org/abs/1807.10957>
- ★ Diversified minibatches for SGD
<https://arxiv.org/abs/1705.00607>
- ★ Diverse sampling in Bayesian optimization
(*Kathuria, Deshpande, Kohli, 2016; Wang, Li, Jegelka, Kohli, 2017*)
- ★ and of course, many more (see tutorial website for more...)

Related work at this conference

- ✓ Derezhinski, Warmuth, Hsu. *Leveraged volume sampling for linear regression*
- ✓ Zhang, Galley, Gao, Gan, Li, Brockett, Dolan. *Generating Informative and Diverse Conversational Responses via Adversarial Information Maximization* (based on MI)
- ✓ Chen, Zhang, Zhou. *Fast Greedy MAP Inference for Determinantal Point Process to Improve Recommendation Diversity*
- ✓ Zhou, Wang, Bilmes. *Diverse Ensemble Evolution: Curriculum Data-Model Marriage*
- ✓ Hong, Shann, Su, Chang, Fu, Lee. *Diversity-Driven Exploration Strategy for Deep Reinforcement Learning* (adds a distance based control)
- ✓ Gillenwater, Kulesza, Vassilvitskii, Mariet. *Maximizing Induced Cardinality Under a Determinantal Point Process*
- ✓ Brunel. *Learning Signed Determinantal Point Processes through the Principal Minor Assignment Problem*
- ✓ Mariet, Sra, Jegelka. *Exponentiated Strongly Rayleigh Distributions*
- ✓ Djolonga, Jegelka, Krause. *Provable Variational Inference for Constrained Log-Submodular Models*

Perspectives

Recent results!

- Strongly log-concave (SLC) polynomials — introduced by Gurvits in 2009, many properties laid out. **Aim**: approximate partition functions over combinatorially large sample spaces
- Properties further developed by Anari, Gharan, Vintant (*Oct & Nov 2018*) and used to solve: Mason's conjecture and more!
- Matroid Base Exchange Walk: Fast Mixing – so in particular, the SR property is not necessary for fast mixing.
- Exponentiated SR measures (*Mariet, Sra, Jegelka, 2018*), with an approximate mixing time analysis and few applications
- The ESR case $0 < \alpha < 1$ falls under the SLC framework, hence fast MCMC sampling (*Anari, Liu, Gharan, Vintant, Nov 2018*)

Summary and outlook

We saw:

Negative dependence as a paradigm in ML
Foundations of strong ND = Strongly Rayleigh
Connections to real stable polynomials
Fast MCMC sampling
Fast approx of partition functions
Many applications

Outlook:

Deeper connections to optimization
Modeling diversity (semi-supervised)
Richer theory of ND sampling
Proving stability of numerous polys still wide-open
Additional applications: from active to interactive
Mixing positive and negative dependence

Thanks



Chengtao Li



Zelda Mariet

Thanks